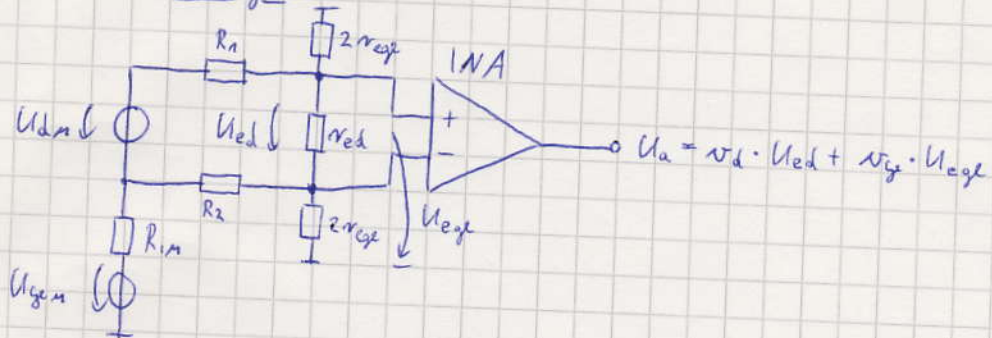


# Instrumentationsverstärker

- Aufgabe:
  - Verstärkung von Differenzspannungen mit einstellbarem  $v$
  - sehr hohe Gleichtaktunterdrückung
  - sehr hoher Eingangswiderstand

## Analyse



$U_{dm}$  ... Messspannung - Nutzsignal

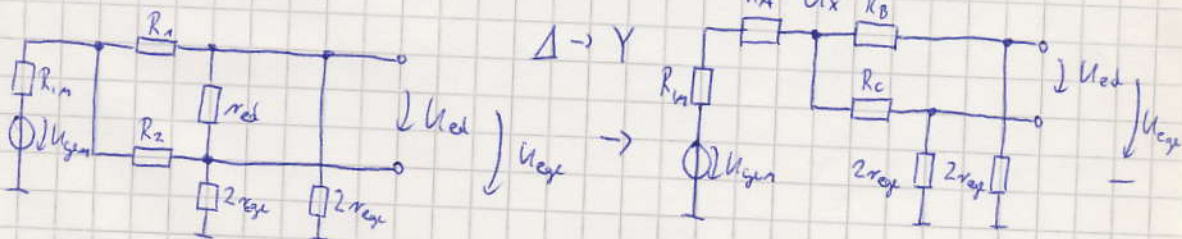
$U_{gem}$  ... Gleichtaktspannung / Störspannung

$R_{in}$  ... Isolationswiderstand des Sensors (Gehäuse-Ende)

$R_{1/2}$  ... Leitungswiderstände, z.B. bei direktem Anschluss des Sensors:  
 $R_1 = R_i(U_{dm})$ ,  $R_2 \ll R_1$  ( $R_2 \rightarrow 0$ )

Approxim:  $R_1, R_2 \ll r_{red}, r_{ref} \rightarrow U_{ed} \approx U_{dm}$

Fehler durch  $r_{red}, r_{ref} < \infty$ :  $\rightarrow$  Gleichtakt  $\rightarrow$  Gegenakt-Wandlung



$r_{red} \Rightarrow R_1, R_2$

$$R_A = \frac{R_1 R_2}{R_1 + R_2 + r_{red}} \approx 0$$

$$R_B = \frac{R_1 r_{red}}{R_1 + R_1 + r_{red}} \approx R_1$$

$$R_C = \frac{R_2 r_{red}}{R_2 + R_2 + r_{red}} \approx R_2$$

$$U_x = U_{gem} \cdot \frac{(R_0 + 2r_{ref}) \parallel (R_C + 2r_{ref})}{R_{in} + (R_0 + 2r_{ref}) \parallel (R_C + 2r_{ref})} \quad (R_A \approx 0)$$

$r_{ref} \Rightarrow R_1, R_2$ :

$$U_x = U_{gem} \cdot \frac{r_{ref}}{R_{in} + r_{ref}}$$

$$U_{ed} = U_x \left( \frac{2r_{ref}}{R_0 + 2r_{ref}} - \frac{2r_{ref}}{R_C + 2r_{ref}} \right) = U_x \left( \frac{2r_{ref}}{R_1 + 2r_{ref}} - \frac{2r_{ref}}{R_2 + 2r_{ref}} \right)$$



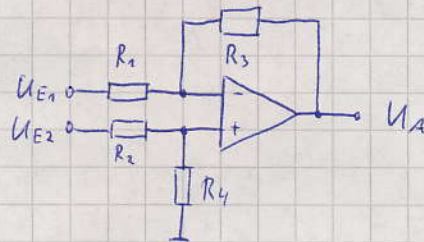
$$U_{ed} = U_x \frac{2r_{ge}(R_2 - R_1)}{(R_2 + 2r_{ge})(R_2 + 2r_{ge})} \approx \frac{R_2 - R_1}{2r_{ge}} \cdot U_x \quad \text{für}$$

$$U_{ed} = \frac{U_{gem}}{2} \cdot \frac{R_2 - R_1}{R_{in} + r_{ge}}$$

$$U_{ge} = \underbrace{\frac{2r_{ge}}{R_{in} + R_c + 2r_{ge}} \cdot U_{gem}}_{\text{nutzlose U-Teiler}} + \underbrace{\frac{U_{gem}}{4} \frac{R_2 - R_1}{R_{in} + r_{ge}}}_{\text{halbe Udiff}} \approx \frac{2r_{ge}}{R_{in} + 2r_{ge}} U_{gem}$$

→  $R_{in}, r_{ge}$  möglichst groß,  $R_2 \approx R_1$

### Instrumentationsverstärker mit 1 OPV



$$+ : U_p = U_{E2} \cdot \frac{R_4}{R_2 + R_4}$$

$$- : U_N = U_{E1} \frac{R_3}{R_1 + R_3} + U_A \cdot \frac{R_3}{R_1 + R_3}$$

idealer OPV:  $U_p = U_N$

$$U_A = \frac{R_1 + R_3}{R_1} \left( U_{E2} \frac{R_4}{R_2 + R_4} - U_{E1} \frac{R_3}{R_1 + R_3} \right) \quad \rightarrow \text{Dimensionierung auf } U_{ge} = 0$$

$$\rightarrow \frac{R_4}{R_2 + R_4} = \frac{R_3}{R_1 + R_3}$$

$$\rightarrow U_A = \frac{R_3}{R_1} (U_{E2} - U_{E1})$$

$$\rightarrow R_1 + R_3 = R_2 + R_4$$

$U_d'$   $U_d'$

$$\hookrightarrow R_1 = R_2, R_3 = R_4$$

$r_{ge, ideal} = 0$

Gleichhaltunterdrückung, real (Ablenkschleife  $R_i$ ,  $G_{ov} < \infty$  - Gleichhaltunterdrückung)

$$R_i = R_{i0} \cdot (1 \pm \delta) \quad i = 1 \dots 4$$

$$G_{ov} = \frac{U_d}{U_{ge}} = CMR$$

Fehler durch  $r_{ge}$ :

$$U_{ge} = U_{ge} \cdot \frac{R_4}{R_2 + R_4}$$

$$U_{A, r_{ge}} = U_{ge} \cdot r_{ge} \cdot \frac{R_4}{R_2 + R_4}$$

$$\left( r_{ge} = \frac{|U_d|}{G_{ov}} + \frac{1}{1 + |U_d|} \right) \quad \leftarrow \text{wird Gese für alle 4 R}$$



$$G = \frac{1}{\frac{1}{G_{ov}} + \frac{46}{|\omega_d| + 1}}$$

Bsp.  $\delta = 0,1\%$

$$|\omega_d| = 1$$

$$\Rightarrow G = 500 \hat{=} 54 \text{ dB}$$

$$G_{ov} = 120 \text{ dB} = 10^6$$

→ 4 hochgenaue R notwendig zur Gleichaktumtreue

- weitere Nachteile: - Regs und Red klein

- zur Änderung von  $\omega'$  sind 2 Rs zu ändern

zoo Common Mode Input Range

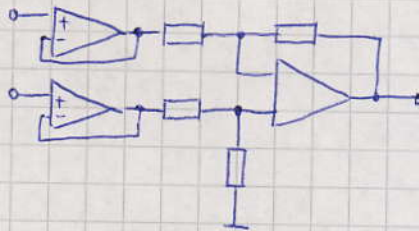
$$U_+ = U_{ge} \frac{R_4}{R_2 + R_4} = U_-$$

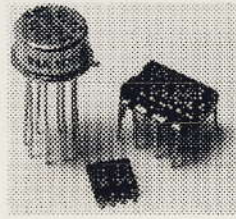
$$U_{+,max} = U_{ge,max} = U_{+,max} \left(1 + \frac{R_2}{R_4}\right) = U_{+,max} \left(1 + \frac{1}{\omega'}\right)$$

für  $\omega' \gg 1$  wird der Gleichaktbereich nicht vergrößert

Folie INA105

Erhöhung des Eingangswiderstandes durch OPV als Spannungsfolger





INA105

## Precision Unity Gain DIFFERENTIAL AMPLIFIER

### FEATURES

- CMR 86dB min OVER TEMPERATURE
- GAIN ERROR: 0.01% max
- NONLINEARITY: 0.001% max
- NO EXTERNAL ADJUSTMENTS REQUIRED
- EASY TO USE
- COMPLETE SOLUTION
- HIGHLY VERSATILE
- LOW COST
- PLASTIC DIP, TO-99 HERMETIC METAL, AND SO-8 SOIC PACKAGES

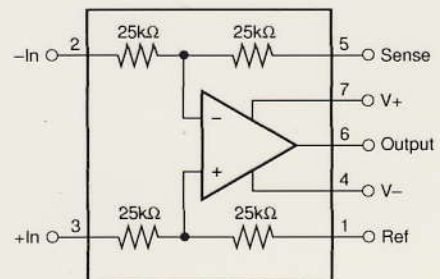
### APPLICATIONS

- DIFFERENTIAL AMPLIFIER
- INSTRUMENTATION AMPLIFIER BUILDING BLOCK
- UNITY-GAIN INVERTING AMPLIFIER
- GAIN-OF-1/2 AMPLIFIER
- NONINVERTING GAIN-OF-2 AMPLIFIER
- AVERAGE VALUE AMPLIFIER
- ABSOLUTE VALUE AMPLIFIER
- SUMMING AMPLIFIER
- SYNCHRONOUS DEMODULATOR
- CURRENT RECEIVER WITH COMPLIANCE TO RAILS
- 4mA TO 20mA TRANSMITTER
- VOLTAGE-CONTROLLED CURRENT SOURCE
- ALL-PASS FILTERS

### DESCRIPTION

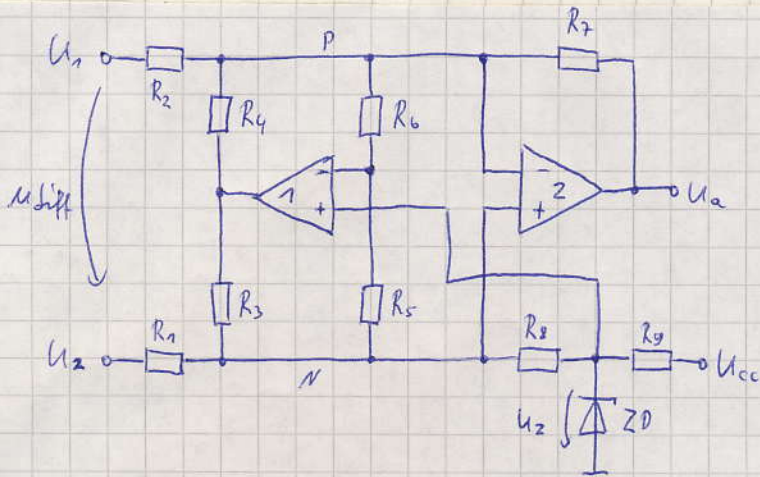
The INA105 is a monolithic Gain = 1 differential amplifier consisting of a precision op amp and on-chip metal film resistors. The resistors are laser trimmed for accurate gain and high common-mode rejection. Excellent TCR tracking of the resistors maintains gain accuracy and common-mode rejection over temperature.

The differential amplifier is the foundation of many commonly used circuits. The INA105 provides this precision circuit function without using an expensive precision resistor network. The INA105 is available in 8-pin plastic DIP, SO-8 surface-mount and TO-99 metal packages.





## 2-OPV Instrumentenverstärker



- $U_Z$  wird in die mitte der Versorgungsspannung gelegt
- $U_{diff2} = 0 \rightarrow \partial_{R5}, \partial_{R6} = 0, U_{diff1} = 0$   
 $U_+ = U_- = U_Z$  für beide OPV

für  $U_1 = U_2 = U_Z \rightarrow \partial_{R1} = \partial_{R2} = 0 \rightarrow \partial_{R7} = 0, U_a = U_Z$

- Gleichtakt - Eingangsspannung:

$\partial_{R1} = \partial_{R2}$  OPV1 stellt den Gleichtakt  $U_p = U_n$  auf  $U_Z$   
 $= \partial_{R3} = \partial_{R4}$

$r_{eqz} = R_1 \parallel R_2$

- Differenzverstärkung

$U_{diff2} = 0$  wegen OPV2 ( $U_p = U_n$ )

$i_{diff} = \frac{U_{diff}}{R_1 + R_2} \Rightarrow r_{eqdiff} = R_1 + R_2$

wegen  $U_1 = U_2 \rightarrow U_{R8} = 0, \partial_{R8} = 0$

$\partial_{R1} = \partial_{R3}, \partial_{R5} = \partial_{R6} = 0$

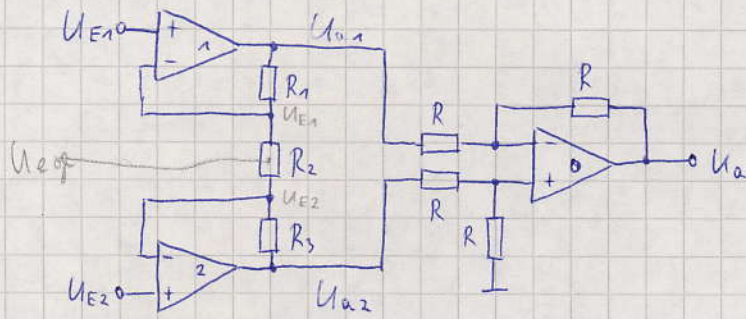
$\partial_{R7} = \partial_{R4} + \partial_{R2} = 2\partial_{R4}$

$\Rightarrow U_a = U_Z - \frac{2 R_7}{R_1 + R_2} \cdot U_{diff}$

- Nur noch  $R_7$  zur Verstärkungseinstellung zu ändern
- andere Bauteile bleiben



### 3-01V Instrumentalverstärker



ideale OPV:

$$w_d' = \frac{U_{a1} - U_{a2}}{U_{E1} - U_{E2}}$$

Question

K5 
$$\frac{U_{a1} - U_{a2}}{R_1 + R_2 + R_3} = \frac{U_{E1} - U_{E2}}{R_2} \rightarrow w_d' = \frac{R_1 + R_2 + R_3}{R_2} = 1 + \frac{R_1 + R_3}{R_2}$$

Gleichtaktverstärkung:

$U_{E1} = U_{E2} = U_{Ege}$ , wegen  $U_d = 0 \rightarrow I_{R2} = 0 \rightarrow U_{a1} = U_{a2} = U_{Ege}$

$w_{ge, in. stufe} = 1$

$w_{ge, ges} = w_{ge, 1} \cdot w_{ge, 0}$

Gleichtaktunterdrückung:

$G' = \frac{w_d'}{w_{ge, 1}} = w_d' = 1 + \frac{R_1 + R_3}{R_2}$  erste Stufe

$G_{ges} = \frac{w_{d, ges}}{w_{ge, ges}} = G' G_0 = w_d' G_0$  gesamt

Nichtideale OPV

- ohne Ableitung

$$\frac{U_{a1} - U_{a2}}{U_{Ege}} = \frac{U_{ad}}{U_{Ege}} \approx w_d' \left( \frac{1}{G_1} - \frac{1}{G_2} \right)$$

- Gleichtakt-Gegentakt-Konversion
- für  $G_1 = G_2 \rightarrow U_{ad} = 0$  keine Gleichtakt-Gegentakt-Konversion

$$w_{ge, ges} = w_{ge, 0} \cdot 1 + w_{d, 0} \cdot w_d' \left( \frac{1}{G_1} - \frac{1}{G_2} \right) \quad w_{d, 0} = 1$$

$$G_{ges} = \frac{w_d'}{w_{ge, 0} + w_d' \left( \frac{1}{G_1} - \frac{1}{G_2} \right)} = \frac{w_d' G_0}{1 + G_0 w_d' \left( \frac{1}{G_1} - \frac{1}{G_2} \right)}$$

Tollu PGA 204

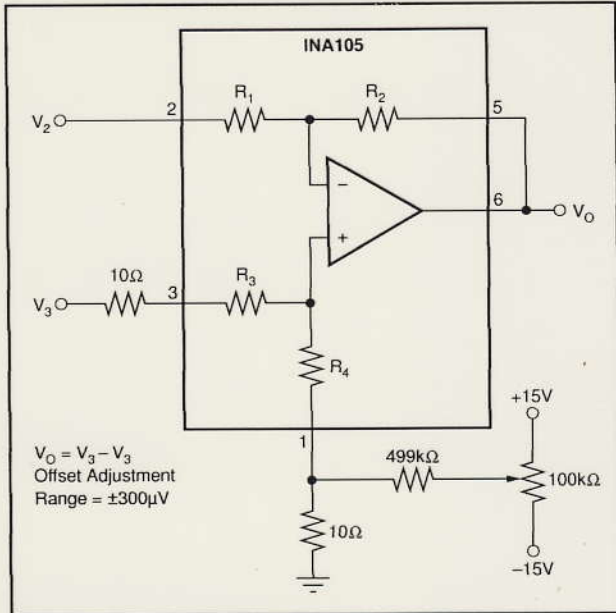


FIGURE 2. Offset Adjustment.

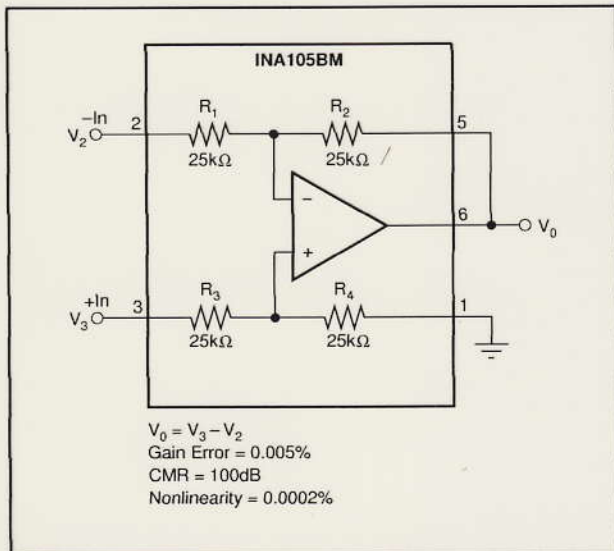
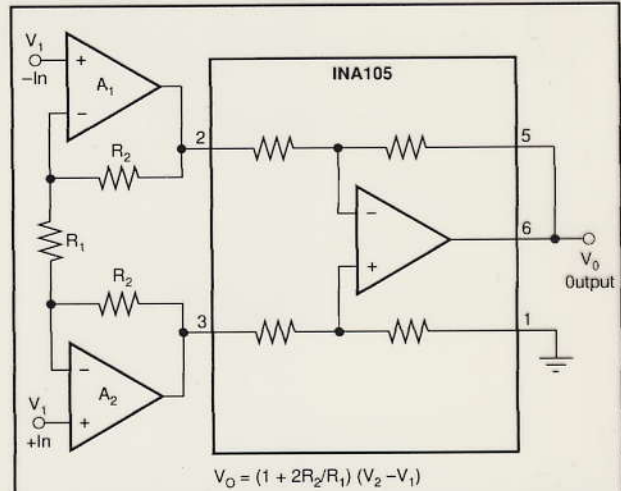


FIGURE 3. Precision Difference Amplifier.



For low source impedance applications, an input stage using OPA27 op amps will give the best low noise, offset, and temperature drift performance. At source impedances above about 10kΩ, the bias current noise of the OPA27 reacting with the input impedance begins to dominate the noise performance. For these applications, using the OPA111 or dual OPA2111 FET input op amp will provide lower noise performance. For lower cost use the OPA121 plastic. To construct an electrometer use the OPA128.

$A_1, A_2$	$R_1$ ( $\Omega$ )	$R_2$ ( $\Omega$ )	GAIN (V/V)	CMRR (dB)	MAX $I_b$	NOISE AT 1kHz (nV/ $\sqrt{\text{HZ}}$ )
OPA27A	50.5	2.5k	100	128	40nA	4
OPA111B	202	10k	100	110	1pA	10
OPA128LM	202	10k	100	118	75fA	38

FIGURE 4. Precision Instrumentation Amplifier.

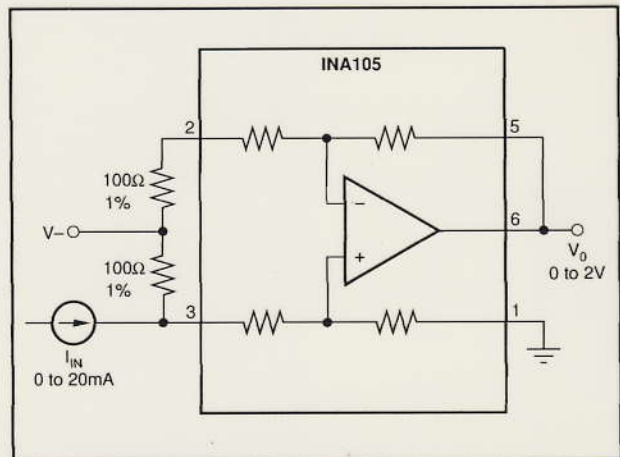
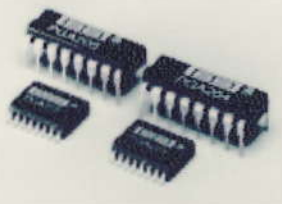


FIGURE 5. Current Receiver with Compliance to Rails.





PGA204  
PGA205

## Programmable Gain INSTRUMENTATION AMPLIFIER

### FEATURES

- **DIGITALLY PROGRAMMABLE GAIN:**  
PGA204:  $G=1, 10, 100, 1000V/V$   
PGA205:  $G=1, 2, 4, 8V/V$
- **LOW OFFSET VOLTAGE:**  $50\mu V$  max
- **LOW OFFSET VOLTAGE DRIFT:**  $0.25\mu V/^\circ C$
- **LOW INPUT BIAS CURRENT:**  $2nA$  max
- **LOW QUIESCENT CURRENT:**  $5.2mA$  typ
- **NO LOGIC SUPPLY REQUIRED**
- **16-PIN PLASTIC DIP, SOL-16 PACKAGES**

### APPLICATIONS

- **DATA ACQUISITION SYSTEM**
- **GENERAL PURPOSE ANALOG BOARDS**
- **MEDICAL INSTRUMENTATION**

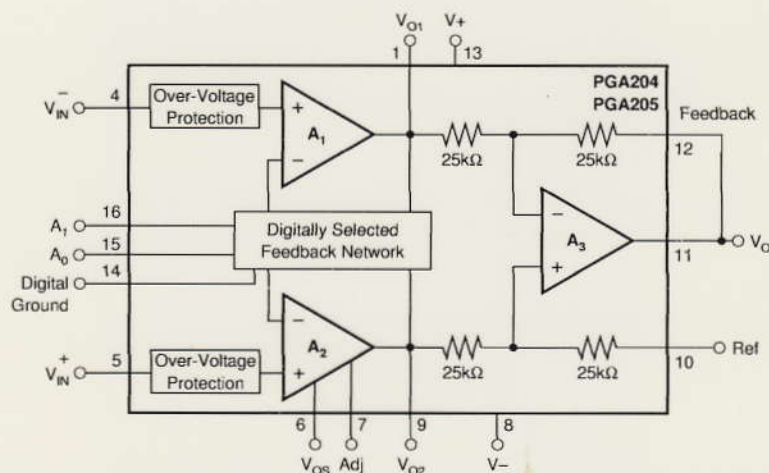
### DESCRIPTION

The PGA204 and PGA205 are low cost, general purpose programmable-gain instrumentation amplifiers offering excellent accuracy. Gains are digitally selected: PGA204—1, 10, 100, 1000, and PGA205—1, 2, 4, 8V/V. The precision and versatility, and low cost of the PGA204 and PGA205 make them ideal for a wide range of applications.

Gain is selected by two TTL or CMOS-compatible address lines,  $A_0$  and  $A_1$ . Internal input protection can withstand up to  $\pm 40V$  on the analog inputs without damage.

The PGA204 and PGA205 are laser trimmed for very low offset voltage ( $50\mu V$ ), drift ( $0.25\mu V/^\circ C$ ) and high common-mode rejection (115dB at  $G=1000$ ). They operate with power supplies as low as  $\pm 4.5V$ , allowing use in battery operated systems. Quiescent current is  $5mA$ .

The PGA204 and PGA205 are available in 16-pin plastic DIP, and SOL-16 surface-mount packages, specified for the  $-40^\circ C$  to  $+85^\circ C$  temperature range.



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# SPECIFICATIONS

## ELECTRICAL

PGA204 G=1, 10, 100, 1000V/V

At  $T_A = +25^\circ\text{C}$ ,  $V_S = \pm 15\text{V}$ , and  $R_L = 2\text{k}\Omega$  unless otherwise noted.

PARAMETER	CONDITIONS	PGA204BP, BU			PGA204AP, AU			UNITS
		MIN	TYP	MAX	MIN	TYP	MAX	
<b>INPUT</b>								
Offset Voltage, RTI vs Temperature	$T_A = +25^\circ\text{C}$		$\pm 10 + 20/G$	$\pm 50 + 100/G$		$\pm 25 + 30/G$	$\pm 125 + 500/G$	$\mu\text{V}$
vs Power Supply	$T_A = T_{\text{MIN}}$ to $T_{\text{MAX}}$		$\pm 0.1 + 0.5/G$	$\pm 0.25 + 5/G$		$\pm 0.25 + 5/G$	$\pm 1 + 10/G$	$\mu\text{V}/^\circ\text{C}$
Long-Term Stability	$V_S = \pm 4.5\text{V}$ to $\pm 18\text{V}$		$0.5 + 2/G$	$3 + 10/G$		*	*	$\mu\text{V}/\text{V}$
Impedance, Differential			$\pm 0.2 + 0.5/G$			*	*	$\mu\text{V}/\text{mo}$
Common-Mode			$10^{10} \parallel 6$			*	*	$\Omega \parallel \text{pF}$
Input Common-Mode Range	$V_O = 0\text{V}$ (see text)	$\pm 10.5$	$10^{10} \parallel 6$			*	*	$\Omega \parallel \text{pF}$
Safe Input Voltage			$\pm 12.7$	$\pm 40$	*	*	*	V
Common-Mode Rejection	$V_{\text{CM}} = \pm 10\text{V}$ , $\Delta R_S = 1\text{k}\Omega$							V
	G=1	80	99		75	90		dB
	G=10	96	114		90	106		dB
	G=100	110	123		106	110		dB
	G=1000	115	123		106	110		dB
<b>BIAS CURRENT</b>								
vs Temperature			$\pm 0.5$	$\pm 2$		*	$\pm 5$	nA
Offset Current			$\pm 8$			*	*	$\text{pA}/^\circ\text{C}$
vs Temperature			$\pm 0.5$	$\pm 2$		*	*	nA
			$\pm 8$			*	*	$\text{pA}/^\circ\text{C}$
<b>NOISE</b> , Voltage, RTI <sup>(1)</sup> : $f = 10\text{Hz}$	$G \geq 100$ , $R_S = 0\Omega$		16			*	*	$\text{nV}/\sqrt{\text{Hz}}$
$f = 100\text{Hz}$	$G \geq 100$ , $R_S = 0\Omega$		13			*	*	$\text{nV}/\sqrt{\text{Hz}}$
$f = 1\text{kHz}$	$G \geq 100$ , $R_S = 0\Omega$		13			*	*	$\text{nV}/\sqrt{\text{Hz}}$
$f_B = 0.1\text{Hz}$ to $10\text{Hz}$	$G \geq 100$ , $R_S = 0\Omega$		0.4			*	*	$\mu\text{Vp-p}$
Noise Current						*	*	
$f = 10\text{Hz}$			0.4			*	*	$\text{pA}/\sqrt{\text{Hz}}$
$f = 1\text{kHz}$			0.2			*	*	$\text{pA}/\sqrt{\text{Hz}}$
$f_B = 0.1\text{Hz}$ to $10\text{Hz}$			18			*	*	$\text{pAp-p}$
<b>GAIN</b> , Error	G=1		$\pm 0.005$	$\pm 0.024$		*	$\pm 0.05$	%
	G=10		$\pm 0.01$	$\pm 0.024$		*	$\pm 0.05$	%
	G=100		$\pm 0.01$	$\pm 0.024$		*	$\pm 0.05$	%
	G=1000		$\pm 0.02$	$\pm 0.05$		*	$\pm 0.1$	%
Gain vs Temperature	G=1 to 1000		$\pm 2.5$	$\pm 10$		*	*	$\text{ppm}/^\circ\text{C}$
Nonlinearity	G=1		$\pm 0.0004$	$\pm 0.001$		*	$\pm 0.002$	% of FSR
	G=10		$\pm 0.0004$	$\pm 0.002$		*	$\pm 0.004$	% of FSR
	G=100		$\pm 0.0004$	$\pm 0.002$		*	$\pm 0.004$	% of FSR
	G=1000		$\pm 0.0008$	$\pm 0.01$		*	$\pm 0.02$	% of FSR
<b>OUTPUT</b>								
Voltage, Positive <sup>(2)</sup>	$I_O = 5\text{mA}$ , $T_{\text{MIN}}$ to $T_{\text{MAX}}$	$(V+) - 1.5$	$(V+) - 1.3$		*	*		V
Negative <sup>(2)</sup>	$I_O = -5\text{mA}$ , $T_{\text{MIN}}$ to $T_{\text{MAX}}$	$(V-) + 1.5$	$(V-) + 1.3$		*	*		V
Load Capacitance Stability			1000			*		pF
Short Circuit Current			$+23/-17$			*		mA
<b>FREQUENCY RESPONSE</b>								
Bandwidth, -3dB	G=1		1			*		MHz
	G=10		80			*		kHz
	G=100		10			*		kHz
	G=1000		1			*		kHz
Slew Rate	$V_O = \pm 10\text{V}$ , G=10	0.3	0.7		*	*		V/ $\mu\text{s}$
Settling Time <sup>(3)</sup> , 0.1%	G=1		22			*		$\mu\text{s}$
	G=10		23			*		$\mu\text{s}$
	G=100		100			*		$\mu\text{s}$
	G=1000		1000			*		$\mu\text{s}$
	G=1		23			*		$\mu\text{s}$
	G=10		28			*		$\mu\text{s}$
	G=100		140			*		$\mu\text{s}$
	G=1000		1300			*		$\mu\text{s}$
Overload Recovery	50% Overdrive		70			*		$\mu\text{s}$
<b>DIGITAL LOGIC</b>								
Digital Ground Voltage, $V_{\text{DG}}$		V-		$(V+) - 4$	*	*		V
Digital Low Voltage		V-		$V_{\text{DG}} + 0.8\text{V}$	*	*		V
Digital Input Current			1			*		$\mu\text{A}$
Digital High Voltage		$V_{\text{DG}} + 2$		$V+$	*	*		V
<b>POWER SUPPLY</b> , Voltage		$\pm 4.5$	$\pm 15$	$\pm 18$	*	*	*	V
Current	$V_{\text{IN}} = 0\text{V}$		$+5.2/-4.2$	$\pm 6.5$	*	*	$\pm 7.5$	mA
<b>TEMPERATURE RANGE</b>								
Specification		-40		+85	*	*	*	$^\circ\text{C}$
Operating		-40		+125	*	*	*	$^\circ\text{C}$
$\theta_{\text{JA}}$			80			*		$^\circ\text{C}/\text{W}$

\* Specification same as PGA204BP.

NOTES: (1) Input-referred noise voltage varies with gain. See typical curves. (2) Output voltage swing is tested for  $\pm 10\text{V}$  min on  $\pm 11.4\text{V}$  power supplies. (3) Includes time to switch to a new gain.



PGA204/205

